# **SVM**S

### PSC8 • PSC16 • PSC24

Multichannel Pressure Scanner Simultaneous acquisition of 8 to 24 pressure signals

- Measuring ranges selectable from 125 Pa to 10bar uni- and bidirectional
- Non-linearity & hysteresis: max. ±0.25% FSS
- Data transfer via USB without external power supply
- CAN bus, LAN and RS232 versions available
- Sampling rate per channel up to max. 50Hz
- Software and driver for LabVIEW and DBC files are included





### **General Description**

The PSC pressure scanners are capable of measuring multiple pressure signals simultaneously. Temperature-compensated transducers feature high accuracy and minimal offset drift. In all devices each pressure channel range can be customized individually according to customer specifications.

The PSC24 has 24 pressure channels. Reference pressure lines of all sensors are connected to a single pressure port in standard configuration. A special differential version with reference ports for each line is also available.

The data is transmitted as ASCII text in the unit Pascal [Pa]. The transmission rate can be set in the range between 1 and 50 Hz.

A tare function can be triggered either by pressing the TARE button or by a software command.

Power for PSC devices equipped with USB or CAN interface is supplied via USB or respectively via CANport. For the version with built-in magnetic valves and LAN interface an external power supply (9-24 V, 1 A) has to be connected with the device.

All PSC versions are equipped with an USB interface, allowing easy configuration. When connected via USB the pressure scanner identifies itself to the host PC as virtual COM port. Thus, any software supporting serial protocols can be used for communication. The LAN-version sends the data using the TCP-IP protocol. A direct connection can be set up via Telnet (Port 10001).

A recording software and an example program in LabVIEW (source code) are shipped with the device. For devices with CAN bus interface a DBC-file is included in the shipment.

On request there are different customization options:

- selection of different sensor pressure ranges
- parallel connection of sensors with different ranges for application where high accuracy is required

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## **Technical Specifications**

Accuracy and scan rates						
Nonlinearity & Hysterese <0.			<0.1% typ. (max. ±0.25	<0.1% typ. (max. ±0.25% FSS)		
Scan rate per channel			1-50 Hz (PSC8: 100Hz)	1-50 Hz (PSC8: 100Hz)		
Power supply						
via USB			USB-powered (no addit	USB-powered (no additional power supply required)		
PSC-LAN	/ PSC-CAN		7-24 V, 50 mA	7-24 V, 50 mA		
Environn	nental conditio	ons				
Temperature			5° C50° C	5° C50° C		
Humidity			095%, non-condensir	095%, non-condensing		
Operating medium			Air and non-corrosive g	Air and non-corrosive gases		
Dimensio	ons					
Housing (	standard)		130 x 55 x 170 mm (B x	130 x 55 x 170 mm (B x H x T)		
Software	and drivers					
Virtual CO	OM-Port-Driver					
Configura	tion software					
LabVIEW-example program as sourcecode						
Supported operation systems						
Windows XP, 7, 8, 10, Linux						
Options						
All PSC s	ystems can be	optionally equ	ipped with CAN bus, LAN or F	RS232		
Pressu	re connectio	ons				
ref.	DI [mm]	DA [mm]	hose material*	Max pressure	Suitable for	
T16	1.3 1.6		Silicone, PE, PVC	0.1MPa	All versions	
T20	1.5 2.0		Silicone	15kPa	All versions	
T25	2.0 2.5		Silicone	15kPa	All with a common reference	
T35	2.5 3.0		Silicone	15kPa	PSC8, PSC16	
P20		2.0	PE, PU, PA	1MPa	PSC8, PSC16	
P30		3.0	PE, PU, PA	1MPa	PSC8, PSC16	
יו וס	ner diameter	-	+ +			

DI Inner diameter

DA Outer diameter

\* recommendation



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#### Pressure ranges

1)	Min <sup>2)</sup>	Max <sup>3)</sup>	Δp <sup>4)</sup>		Proof <sup>5)</sup>	Burst <sup>6)</sup>	
			Bi-	direktiona			
D	-125	125	0,02	[Pa]	25	75	[kPa]
D	-250	250	0,04	[Pa]	25	57	[kPa]
D	-500	500	0,07	[Pa]	25	57	[kPa]
D	-1,25	1,25	0,0002	[kPa]	50	57	[kPa]
D	-2,5	2,5	0,0004	[kPa]	50	57	[kPa]
D	-5,0	5,0	0,0007	[kPa]	50	125	[kPa]
D	-7,5	7,5	0,001	[kPa]	50	125	[kPa]
D	-15	15	0,002	[kPa]	50	200	[kPa]
D	-25	25	0,004	[kPa]	100	100	[kPa]
D	-50	50	0,008	[kPa]	100	100	[kPa]
D	-100	100	0,015	[kPa]	300	1000	[kPa]
D	-250	250	0,04	[kPa]	720	1700	[kPa]
D	-500	500	0,08	[kPa]	1200	1700	[kPa]
D	-1000	1000	0,16	[kPa]	1700	1700	[kPa]
Uni-directional							
D	0	250	0,02	[Pa]	25	75	[kPa]
D	0	500	0,04	[Pa]	25	75	[kPa]
D	0	1,25	0,0001	[kPa]	50	75	[kPa]
D	0	2,5	0,0002	[kPa]	50	75	[kPa]
D	0	5,0	0,0004	[kPa]	50	125	[kPa]
D	0	7,5	0,0005	[kPa]	50	125	[kPa]
D	0	15	0,001	[kPa]	50	200	[kPa]
D	0	25	0,002	[kPa]	100	100	[kPa]
D	0	50	0,004	[kPa]	100	100	[kPa]
D	0	100	0,008	[kPa]	300	1000	[kPa]
D	0	250	0,02	[kPa]	720	1700	[kPa]
D	0	500	0,04	[kPa]	1200	1700	[kPa]
D	0	1000	0,08	[kPa]	1700	1700	[kPa]
	Absolute						
А	0	34	0,003	[kPa]	100	100	[kPa]
Α	0	100	0,007	[kPa]	200	1,0	[MPa]
Α	0	200	0,013	[kPa]	800	1,7	[MPa]
А	0	400	0,025	[kPa]	1,3	1,7	[MPa]
Α	60	110	0,004	[kPa]		1,7	[MPa]

- 1. D: differential. Pressure difference can be applied via 2 connections. The reference port (min) of multiple sensors can also be combined on one connection
- 2. A: absolute. Measurement of absolute pressure, an open pressure port indicates the barometric air pressure, if the pressure is within the measuring range
- 1) Nominal smallest possible value
- 2) Nominal highest possible value
- 3) Resolution of digitization (rounded)
- 4) Maximum pressure that does not yet cause damage to the sensor
- 5) Maximum differential pressure against environment that the internal sensor housing can withstand. At a higher pressure, the housing may crack. However, damage to the sensor occurs when the PROOF pressure is reached.

The measurement uncertainty is 0.25% of the measuring range (span min max). During factory calibration, a deviation from the nominal value significantly smaller than 0.1% of the measuring range is achieved.

### **Serial Interface**

The virtual COM port can be operated at any baud rate. We recommend 19200, 8 data bits, no parity, 1 stop bit. **DTR (Data Terminal Ready) must be asserted.** 

Command	Function	Answer
CAL a x	Set scaling factor for sensor a to value x	#Scaler= Offset=
CAL? A	Read scaling factors for sensor a	#Scaler= Offset=
EE_LOAD	Load calibration data from EEPROM	#EEPROM:loaded
EE_SAVE	Save calibration data to EEPROM	#EEPROM:saved
*IDN?	Read device ID	#PSC24-LAN 2.4.0 #SN35000
RATE X	Define sample rate range x = 20 …5000 [ms] standard: 1000 [ms] → 1 [Hz]	#Rate=x ms #Error: Rate-Range
rate O	Activate request and trigger mode actual values are read only after manual command "?" is sent	#Request-Mode active
?	Read actual value (request-mode only)	
*RST	Load default settings	#RESET
SCAN_A x SCAN_B x SCAN_C x	Defines a scanlist (channel selection) binary, each bit represents one channel	
TARA	Zero adjustment for all sensors	#TARA
FILTER x	Activate exponential filter 0 = deactivated; >0 = filter ranage in ms	#FILTER=x

starts at 1.

-for CAN bus version only-					
CAN_ID x	Set CAN-ID	#OK			
_	Set interface x = 0: normal (11 bit, CAN 2.0A) x = 1 extended 23 bit (23 bit, CAN 2.0B)	#OK			
CAN?	Request CAN configuration	<pre>#ID:0x[]_Speed:[baud]_IDT: [0,1]</pre>			
	Set CAN bus rate 0: 125 kBaud 1: 250 kBaud 2: 500 kBaud 3: 1 MBaud	#OK			



## **Technical Drawing**

Dimensions for a PSC24 device can be taken from the following drawing.

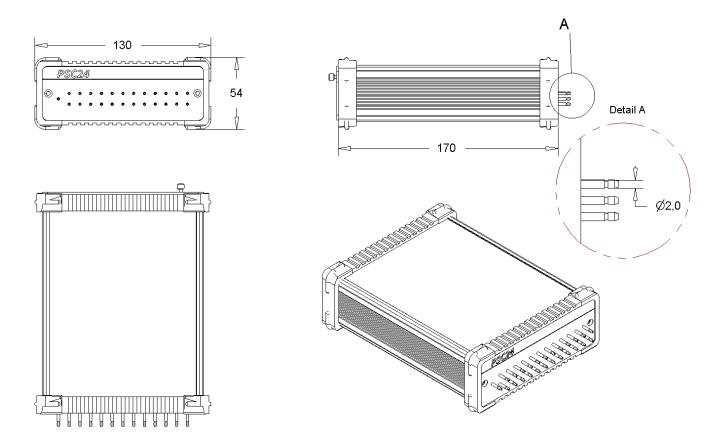


Figure: technical drawing and dimensions for a PSC24 pressure scanner.

### **Examples of custom devices**

Devices with two separate reference ports, on the right additionally with 0-7bar

